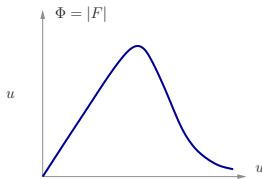
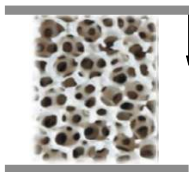


Physical response of random networks generated from the same random graph



$$\Phi = f_{\Phi}(\dots, \underbrace{\gamma_1, \dots, \gamma_L}_{\text{geometry}}, \underbrace{\theta_1, \dots, \theta_K}_{\text{topology}})$$

Options for trying to specify $\Phi = f_{\Phi}(\dots, \underbrace{\gamma_1, \dots, \gamma_L}_{\text{geometry}}, \underbrace{\theta_1, \dots, \theta_K}_{\text{topology}})$:

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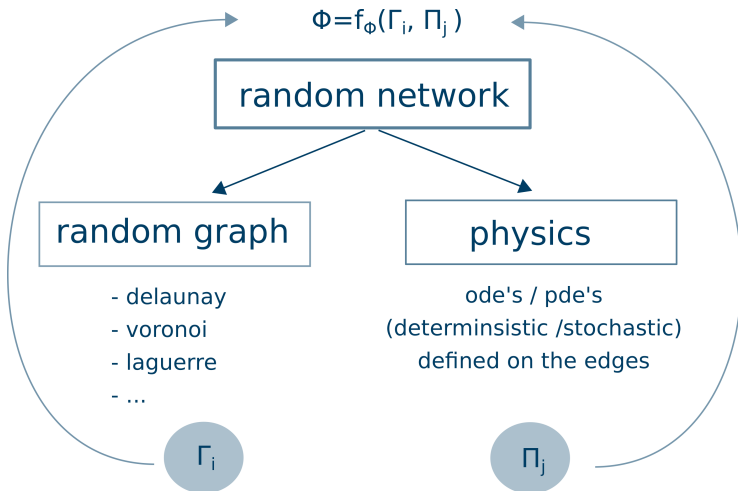
- 1 Deduce dependencies analytically by logical reasoning.
 - requires almost transcendental cognitive skills

Options for trying to specify $\Phi = f_{\Phi}(\dots, \underbrace{\gamma_1, \dots, \gamma_L}_{\text{geometry}}, \underbrace{\theta_1, \dots, \theta_K}_{\text{topology}})$:

- ➊ Deduce dependencies analytically by logical reasoning.
 - requires almost transcendental cognitive skills
- ➋ Perform large amount of real and virtual experiments.
 - decisions about what to vary and how
 - time and resource consuming
 - processing of a large amount of data

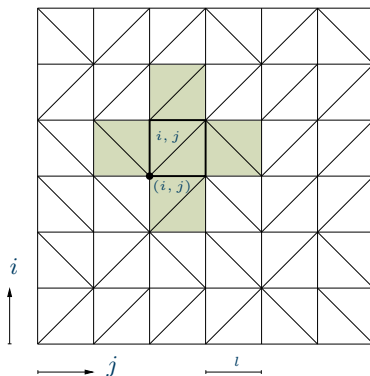
Options for trying to specify $\Phi = f_{\Phi}(\dots, \underbrace{\gamma_1, \dots, \gamma_L}_{\text{geometry}}, \underbrace{\theta_1, \dots, \theta_K}_{\text{topology}})$:

- 1 Deduce dependencies analytically by logical reasoning.
 - requires almost transcendental cognitive skills
- 2 Perform large amount of real and virtual experiments.
 - decisions about what to vary and how
 - time and resource consuming
 - processing of a large amount of data
- 3 Define and study rigorously simplified problems first.
 - investigation methodology
 - eventually a smarter version of option 2



Parent Graph

(0 graph)



discrete field ξ on a lattice:

$$\xi_{i,j} = \begin{cases} 0 & \text{if diagonal} \end{cases} \quad \left\langle \begin{array}{l} / \\ \backslash \end{array} \right.$$

ratio between / and \ diagonals $\rightarrow \rho$:

$$\rho = \frac{1}{M^2} \sum_{i,j} \xi_{i,j}$$

$$\bar{\rho} = \min(\rho, 1 - \rho) \in [0, 0.5]$$

nearest neighbor correlation $\rightarrow \mu$:

$$\mu = \frac{1}{M^2} \sum_{i,j} \sum_{\substack{k,l \\ d=1}} \mathbb{1}(\xi_{i,j} \neq \xi_{k,l})$$

$$\text{with } d = |k - i| + |l - j|$$

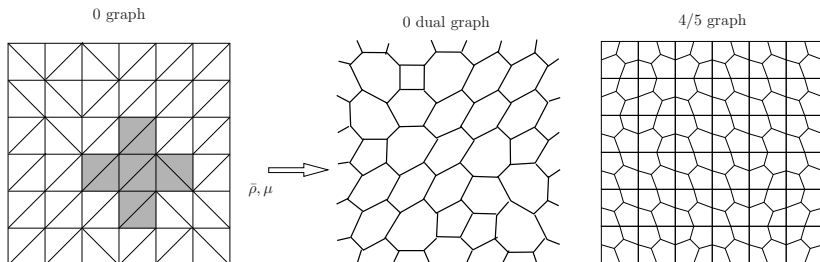
Sampling procedure

- set of all possible configurations $\mathcal{C} = \{X_1, X_2, \dots, X_{2^{M^2}}\}$
- probability of finding a configuration $X_k \in \mathcal{C}$

$$P(X = X_k) = \frac{1}{\mathcal{Z}} \exp(-\beta \mu(X_k))$$

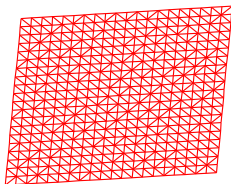
- \mathcal{Z} : partition function which ensures that $\sum_{i=1}^{2^{M^2}} P(X = X_i) = 1$
- β : scalar parameter which controls the sampling procedure
- sampling according to $P(X)$ for fixed $\bar{\rho}$ using Metropolis
- bijective relation $\mu \leftrightarrow \beta$

Derived graphs

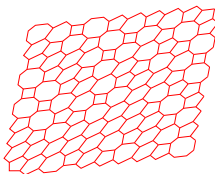


Networks: physics → deformation, response → strain energy

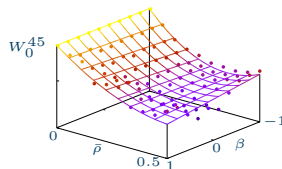
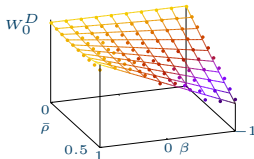
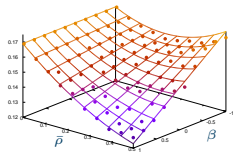
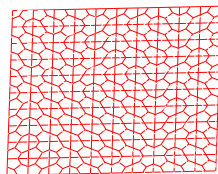
truss - 0



beam - 0 dual



beam - 45

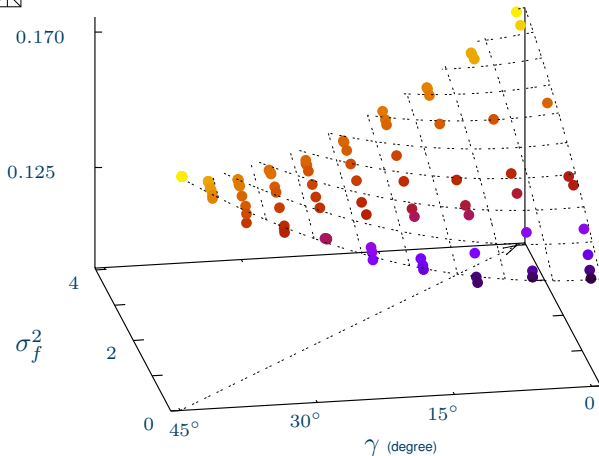


$$+) \tan \alpha_e = \frac{\sum l_e \sin \alpha_e}{\sum l_e \cos \alpha_e}$$

trial for 0 dual and 4/5 graph: s_R and I_{12}

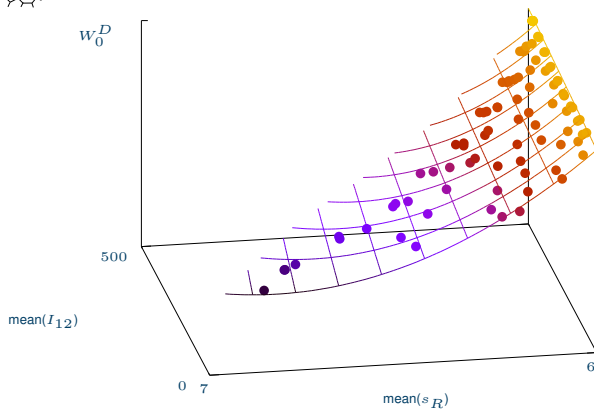
Results

truss - 0



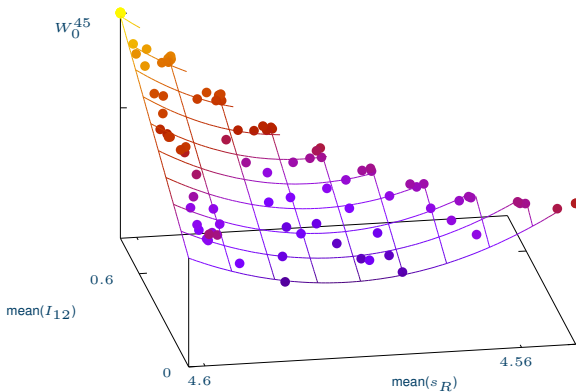


beam - 0 dual





beam - 4/5



Summary

- networks derived from 0 graph:

$$\Phi = f_{\Phi}(\mathbb{E}, \bar{\rho}, \mu) \Rightarrow \begin{array}{ll} f_{\Phi}^{\Delta}(\mathbb{E}, \text{var}(n_d), \alpha) & \text{ode 2} \\ f_{\Phi}^{\diamond}(\mathbb{E}, \text{mean}(s_d), \text{mean}(I_{12})) & \text{ode 4} \end{array}$$

- so far: 1 topological measure and 1 geometrical measure
- suspiciously simple - most likely because physics rather simple
 - linear
 - \mathbb{E} (e.g. no overall bending)
 - time independent

to be traced back to parent graph

$$\bar{\rho}, \mu \quad \text{complexity} \uparrow \quad \bar{\rho}, \mu, \dots?$$

- reasonable methodology for performing numerical experiments

Outlook

- analytical estimates

- e.g., mean field

$$\underline{\underline{K}} \cdot \underline{u} = \underline{b} \quad \longrightarrow \quad \underline{\underline{K}}^* \cdot \langle \underline{u} \rangle = \underline{b} \quad \text{with} \quad \underline{\underline{K}}^* = \langle \underline{\underline{K}} \rangle + \underline{\underline{K}}_0^{-1} \text{var}(\underline{\underline{K}})$$

- linear transport (work in progress)

$$\underline{\underline{K}} = \underline{\underline{D}} - \underline{\underline{A}} \quad , \quad n_d, s_d \rightarrow \langle \underline{\underline{D}} \rangle, \langle \underline{\underline{A}} \rangle, \text{var}(\underline{\underline{D}}), \dots$$

- physics:

- linear / nonlinear transport
- fracture
- dynamics

- more general cases

$$\begin{array}{ccc} \text{Delaunay} & & \text{var}(n_d), \alpha_e \\ & \longrightarrow & \\ \text{Voronoi / Laguerre} & & \text{mean}(s_R), \text{mean}(I_{12}) \end{array}$$